

Simulating Large-scale Dynamic Random Graphs in OMNeT++

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Introduction and motivation

- *Networked communications systems* are an important research topic.
- *New paradigms* impact our everyday lives in new and sometimes unforeseen ways.
- Can expect distributed systems to grow both in *number* and *scale*.
 - ▶ wireless sensors
 - ▶ collaborative sensing and sharing
 - ▶ the internet of things
 - ▶ ...



The case for simulation

- New protocols and distributed applications require careful evaluation.
 - **Notoriously hard to test.**
 - ▶ Repeatability
 - ▶ Access to testbeds
 - ▶ Practical size limitations of testbeds
 - ▶ ...
 - **Simulation is an important tool for analysis**
-
- We can specify a *fine grained model*:
 - ▶ Mobility characteristics
 - ▶ Full protocol stack
 - ▶ Detailed infrastructure
 - ▶ ...
 - **Highly domain specific**



The case for random graph based simulation

- We may want to model at a more *abstract* level using some general but realistic system assumptions.
- Handy tool: **Random graph models**
 - ▶ Simulations of networked systems are based on an *underlying network graph*
 - ▶ Random graph models may be applied in case of a non-deterministic network.

Approach

- Construct a high-level *approximation* of a networked system by picking an appropriate *generation algorithm* and *parameters*.
 - ▶ **Size/scale**
 - ▶ **Dynamism**, e.g. mobility – VANETs, MANETs, pedestrian networks.
 - ▶ **Comm links**: range, capacity, protocol, loss model.
 - ▶ **Means of establishing links**: Graph connectivity, degree distribution.
 - ▶ ...

Random graphs and generation algorithms

Definition

Random graph. A *random graph* is a graph $G = (V, E)$ in which vertices and edges are determined by some random process.

Random graph generators

The *algorithms* used to construct random graphs.

- **Binomial graphs** – Erdős-Rényi.
- **Small world models** – e.g. Watts-Strogats
- **Scale-free models** – e.g. Barabási-Albert

Our objective

*Present an approach and a **set of components** to enable dynamic generation and maintenance of random graphs at **runtime** within OMNeT++.*

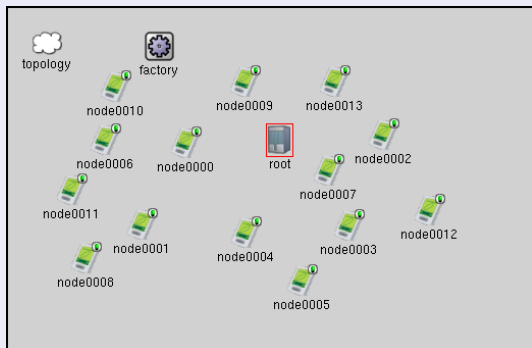
<https://github.com/kristjanvj/DRGSimLib>

The simulation toolbox

Components

- **Nodes** – a compound node representing simulated objects
- **Node factory** – manages lifetime of nodes
- **Topology** – manages node relations – the *network graph*

Sample scenario



The node factory – Factory

- *Dynamic* instantiation and destruction of **nodes**
- Operates *independently* of the graph generation

Parameters

nodeType The class name of a OMNeT++ compound module – the type of node to be manufactured.

generateInterval The node generation interval.

lifetime The lifetime of generated nodes.

minLifetime The minimum lifetime of generated nodes.

Volatile parameters – can plug in OMNeT++ standard random functions in ini file.



Topology management – Topology

- Flexible generation/maintenance of random graphs.
- Architecture:
 - ▶ *controller*
 - ▶ a plug-in generator instance

Parameters

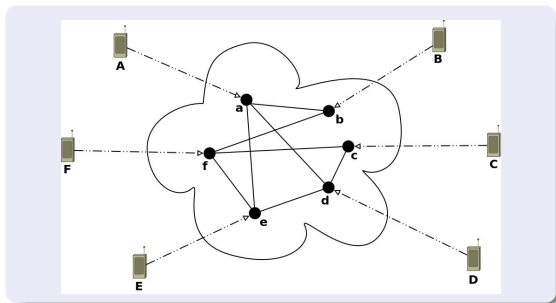
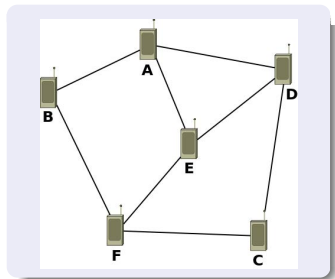
`topologyGenerator` The name of a topology generator class implementing the `IBasicGenerator` interface.

`updateInterval` The interval in seconds between updates of the edge structure of the graph.

`snapshotFile` The name of a file for storing snapshots of the graph topology for off-line analysis.



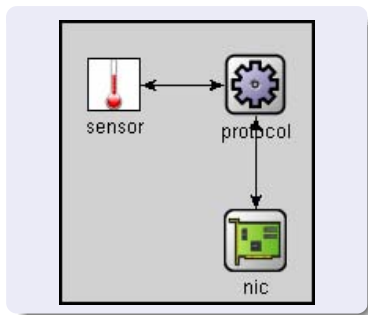
Representing a communications model as a graph



- Communications network represented by a *single data structure*
 - ▶ managed by the *controller*
 - ▶ via algorithms implemented in the *plug-in generator*
- Direct message passing (with delay) between nodes
 - ▶ \Rightarrow *Minimal message object generation*



A sample node



- **Node**: the simulated object
- **NIC** required



The TopologyControlNIC

Parameters

`dataRate` The data rate in Kbps.

`bitErrorRate` A volatile parameter for the bit error rate.

`processingDelay` The processing delay in seconds.

`propagationDelay` The propagation delay in seconds.

- The **per-node** counterpart to the `topologyControl`
- *Registers* the host node with `Topology` upon instantiation
- *De-registers* upon destruction
- Stores *local neighbourhood view*



Plug-ins for graph generation and management

- The **graph generator** is a *plug-in* instantiated at start of simulation via ini file parameter.
- Derived from a *base class*, implementing `IBasicGenerator` interface.
- Users can derive their own random graph generator classes

`IBasicGenerator`

`addNode` Adds a vertex to the graph data structure and creates edges in accordance with the implemented algorithm.

`void removeNode` Removes a vertex from the graph. All incident edges are also removed.

`bool update` Periodic updates of the graph edges to simulate dynamic effects other than node churn.

`void constructInitialTopology` Called after initialization of the topology manager to create edges between nodes instantiated at time zero.

Binomial graph generation

The binomial graph $g_{n,p}$, also known as a Erdős-Rényi graph.

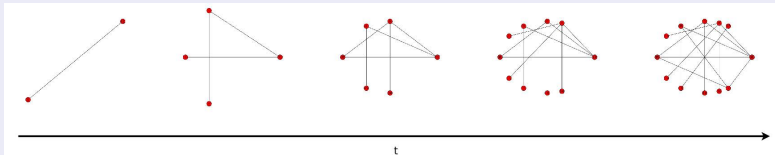
Generation algorithm

Generate n nodes $\in V$. For a node $v \in V$, create an edge $e = (u, v) \in E$ with probability p to each node $u \in V \setminus v$.



$g_{n,p}$ insertion of nodes

```
{Upon registration of node  $v$ }  
insert  $v$  into  $V$ , the vertices collection  
if  $|V| = 1$  then  
    return  
else if  $|V| = 2$  then  
    createLink( $u,v$ )  
else  
    select node  $u \in V$  uniformly at random.  
    createLink( $u,v$ )  
    for each  $z \in V \setminus u$  do  
        createLink( $v,z$ ) with probability  $p$   
    end for  
end if
```



$g_{n,p}$ graph maintenance

{Executed periodically, T_Δ is the time units since last update.}

$p_r \leftarrow T_\Delta \cdot p_c$

$p_a \leftarrow T_\Delta \cdot p_c \cdot |E|/|V|$

for each $e \in E$ **do**

 remove e with probability p_r

end for

for each $v \in V$ **do**

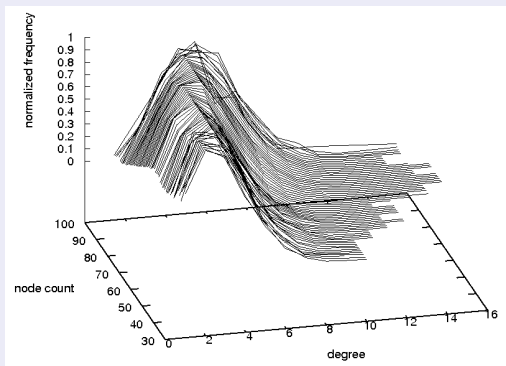
 do with probability p_a : pick a neighbor $u \in V \setminus v$ uniformly at random and add edge (v, u)

end for



A small $g_{n,p}$ graph evolution experiment

Average degree distribution



- Note the characteristic *Poisson* shape of the curves
- Not scale-free

Barabási-Albert (BA) graph generation

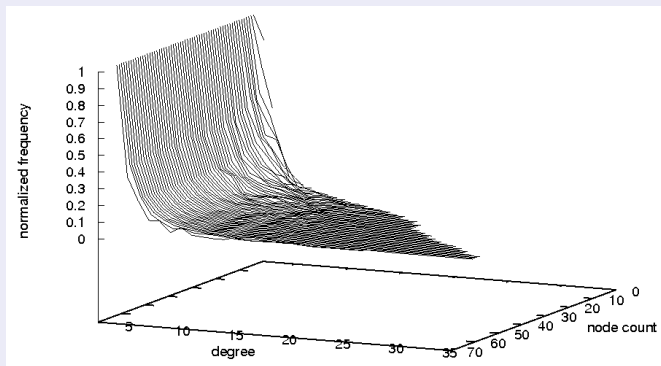
Generation algorithm

Generate a new node v in the graph $G = (V, E)$. For the node v , create an edge $e = (u, v)$ with any peer $u \in V \setminus v$ with probability $p(u) = k_u / \sum_{z \in V} k_z$, where k_z is the degree of a node $z \in V$.



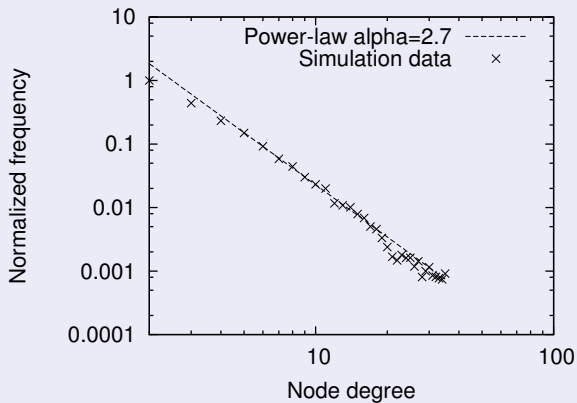
A small BA graph evolution experiment

Average degree distribution



- Distinctive *power-law* shape
- **Scale-free?**

Power law characteristics of a BA graph



Problematic effects of graph dynamism

- *Dynamism* \Rightarrow graph connectivity not guaranteed
- Fact of life but **complicates** analysis
- Topology *optionally* guarantees connectivity

- (i) Cut vertices
- (ii) Cut edges

Remedy

- 1 Search k -neighbourhood recursively to determine connectivity.
- 2 Connect components which have not been confirmed as connected.



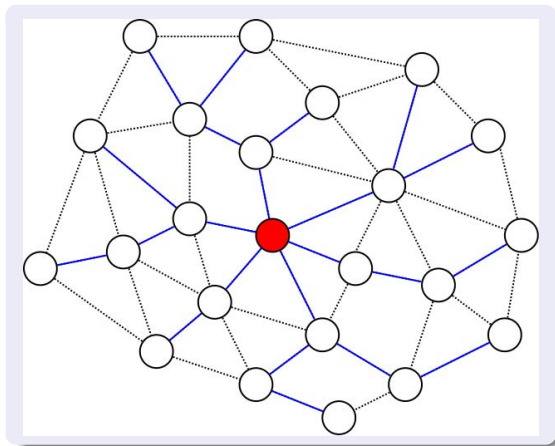
Application example: GAP

- The Generic Aggregation Algorithm – GAP¹.
- Designed for *network monitoring applications*
- Continuous monitoring in *dynamic* networks.
- Distributed construction and maintenance of a spanning-tree overlay – the aggregation overlay.

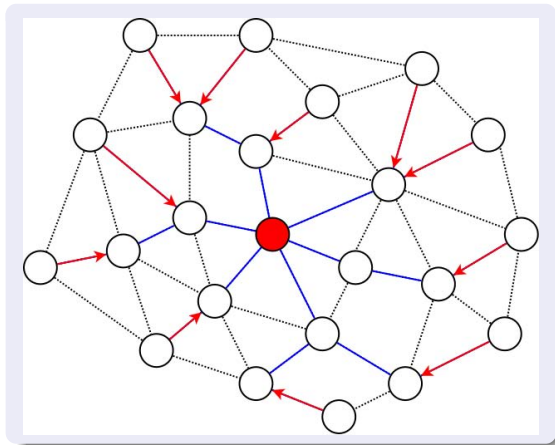
Dam, M. & Stadler, R., *A generic protocol for network state aggregation*.
In Proc. Radiovetenskap och Kommunikation (RVK), pp. 14–16, Linköping,
Sweden. 2005.



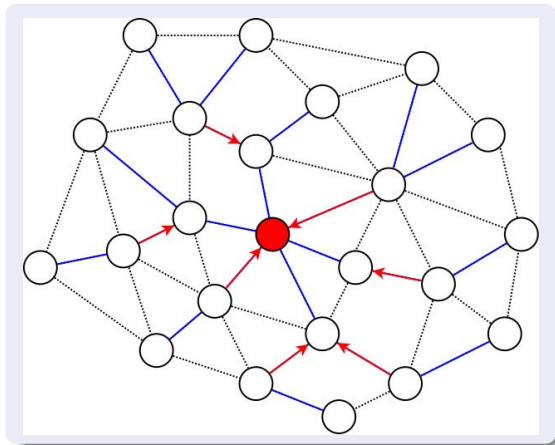
In-network computation



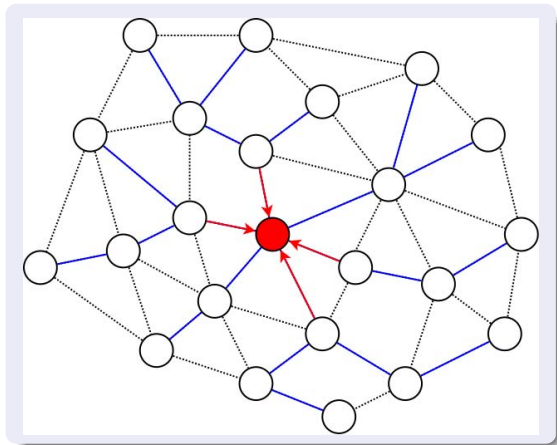
In-network computation



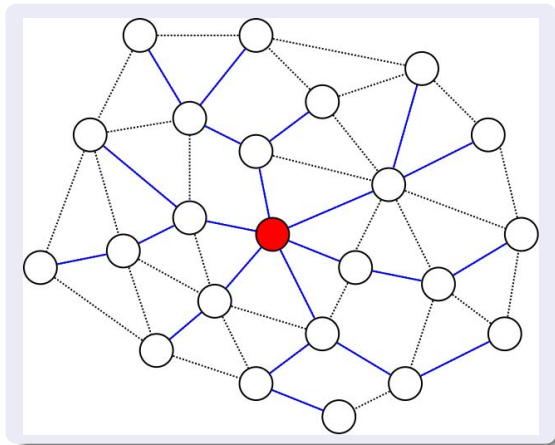
In-network computation



In-network computation



In-network computation



- Each node provides updates on *own* schedule
- Example shows *synchronous operation* for simplicity
- Recipients of updates compute *new contributions in-network*

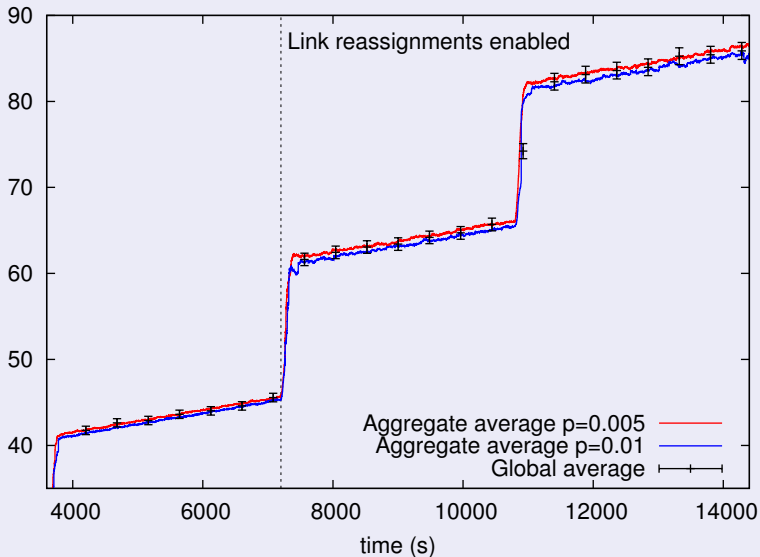
Constant node population

Experimental setup

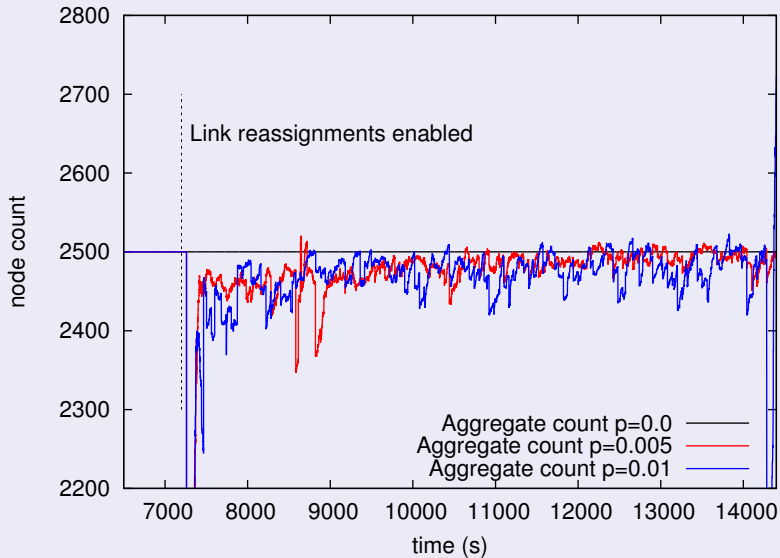
- BA graph, $m_0 = 5$, $m = 3$
- 2500 nodes, static population
- Dynamic link reassignments in window $t = [2h, 4h]$.
- Failure detection latency: $1s + \mathcal{N}(0s, 1s)$.



Aggregate – AVERAGE



Aggregate – COUNT



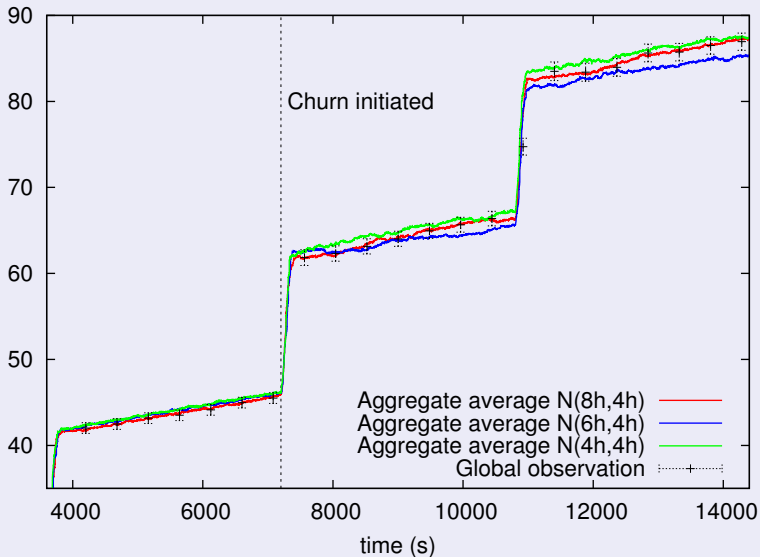
Dynamic node population

Experimental setup

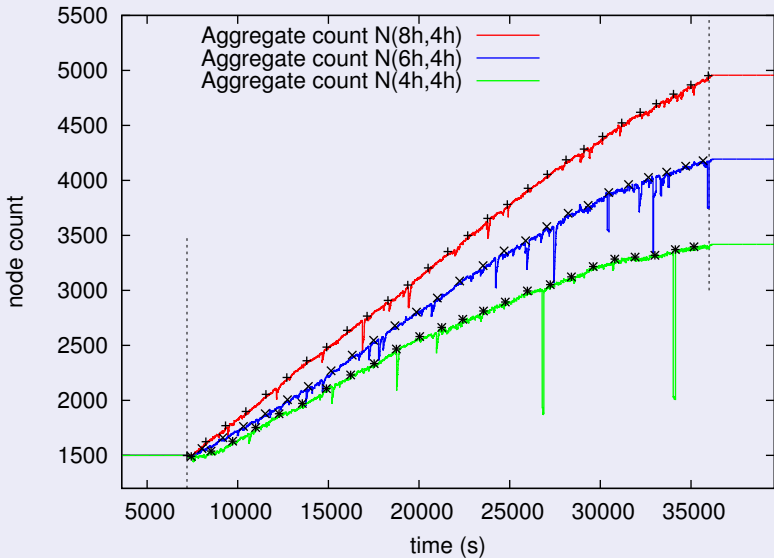
- BA graph, $m_0 = 5$, $m = 3$
- 1500 nodes at time zero
- Poisson arrivals with $1/\lambda = 5s$.
- Node lifetime drawn from $\mathcal{N}(\mu, \sigma)$
- Initial node lifetime (zero population) drawn from uniform $[0, \mu]$ distribution.
- Churn interval $t = [2h, 10h]$
- Failure detection latency: $100ms + \mathcal{N}(0s, 100ms)$.



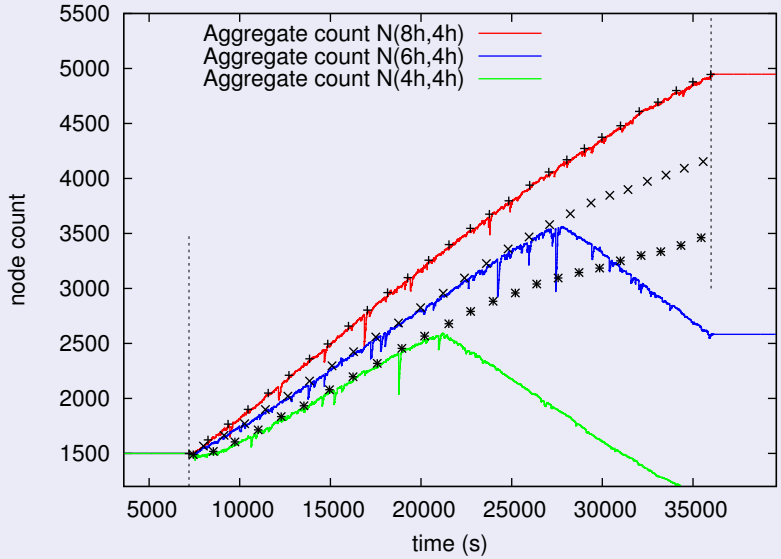
Aggregate – AVERAGE



Aggregate – COUNT



Aggregate – COUNT. Slow failure detection.



failure detection: $1s + \mathcal{N}(0s, 1s)$.

Conclusions

- **Motivation:** Allow easy construction of random-graph based simulations in OMNeT++
 - ▶ Abstract away from complexities of networks/systems, providing means of evaluating protocols with emphasis on end systems.
- **Toolbox:** Provide a set of components to facilitate simulation based on *random graph models* in OMNeT++
 - ▶ **Generic node class** (example only)
 - ▶ **Node factory**
 - ▶ **Topology manager** with **plug-in generators**
- **Demonstration application:** **GAP dynamic aggregation protocol.**
- **Generally applicable** tool for graph-based simulation research
 - ▶ May even be used for applications unrelated to physical networks.
 - ▶ **OMNeT++ as a tool to study social networks?**

